Python with Robots Mission 6 Lab Da	et – OBJ 3, 4,	, 5	Name:		
					hold and reflecting surface? ces. Write down the results.
Threshold (start with 2500) Reflective s		Reflective sur	rface Sens		r reading (true or false)
Obj 4 (Get a new threshold): For Objective #4, you need to determine a new threshold for the sensors. Using REPL and the Console Panel, start with Is.check(0) . See the range of raw values for your line/ground area. Try different threshold values until you find the one that works best with Is.check() .					
Start with Is.check(0) What is the range of rav					
Now choose different values as a threshold :			Result:		
Obj 5 (Between the edges: For Objective #5, you want to experiment with different curves and turns.					
Speed of 'bot Turn code (L / R)		Type of Curve		Result:	